Simple Class A Amplifier

A 10-W design giving subjectively better results than class B transistor amplifiers

by J. L. Linsley Hood, M.I.E.E.

During the past few years a number of excellent designs have been published for domestic audio amplifiers. However, some of these designs are now rendered obsolescent by changes in the availability of components, and others are intended to provide levels of power output which are in excess of the requirements of a normal living room. Also, most designs have tended to be rather complex.

In the circumstances it seemed worth while to consider just how simple a design could be made which would give adequate output power together with a standard of performance which was beyond reproach, and this study has resulted in the present design.

Output power and distortion

In view of the enormous popularity of the Mullard "5-10" valve amplifier, it appeared that a 10-watt output would be adequate for normal use; indeed when two such amplifiers are used as a stereo pair, the total sound output at full power can be quite astonishing using reasonably sensitive speakers.

The original harmonic distortion standards for audio amplifiers were laid down by D. T. N. Williamson in a series of articles published in Wireless World in 1947 and 1949; and the standard, proposed by him, for less than 0.1% total harmonic distortion at full rated power output, has been generally accepted as the target figure for high-quality audio power amplifiers. Since the main problem in the design of valve audio amplifiers lies in the difficulty in obtaining adequate performance from the output transformer, and since modern transistor circuit techniques allow the design of power amplifiers without output transformers, it seemed feasible to aim at a somewhat higher standard, 0.05% total harmonic distortion at full output power over the range 30Hz-20kHz. This also implies that the output power will be constant over this frequency range.

Circuit design

The first amplifier circuit of which the author is aware, in which a transformerless transistor design was used to give a standard of performance approaching that of the "Williamson" amplifier, was that published in Wireless World in 1961 by Tobey and Dinsdale. This employed a class B output stage, with series connected transistors in quasi-complementary symmetry. Subsequent high-quality transistor power amplifiers have largely tended to follow the design principles outlined in this article.

The major advantage of amplifiers of this type is that the normal static power dissipation is very low, and the overall power-conversion efficiency is high. Unfortunately there are also some inherent disadvantages due to the intrinsic dissimilarity in the response of the two halves of the push-pull pair (if complementary transistors are used in unsymmetrical circuit arrangement) together with some cross-over distortion due to the Ic/Vb characteristics. Much has been done, particularly by Bailey¹, to minimise the latter.

An additional characteristic of the class B output stage is that the current demand of the output transistors increases with the output signal, and this may reduce the output voltage and worsen the smoothing of the power supply, unless this is well designed. Also, because of the increase in current with output power, it is possible for a transient overload to drive the output transistors into a condition of thermal runaway, particularly with reactive loads, unless suitable protective circuitry is employed. These requirements have combined to increase the complexity of the circuit arrangement, and a well designed low-distortion class B power amplifier is no longer a simple or inexpensive thing to construct.
An alternative approach to the design of a transistor power amplifier combining good performance with simple construction is to use the output transistors in a class A configuration. This avoids the problems of asymmetry in quasi-complementary circuitry, thermal runaway on transient overload, cross-over distortion and signal-dependent variations in power supply current demand. It is, however, less efficient than a class B circuit, and the output transistors must be mounted on large heat sinks.

The basic class A construction consists of a single transistor with a suitable collector load. The use of a resistor, as in Fig. 1(a), would be a practical solution, but the best power-conversion efficiency would be about 12%. An l.f. choke, as shown in Fig. 1(b), would give much better efficiency, but a properly designed component would be bulky and expensive, and remove many of the advantages of a transformerless design. The use of a second, similar, transistor as a collector load, as shown in Fig. 1(c), would be more convenient in terms of size and cost, and would allow the load to be driven effectively in push-pull if the inputs of the two transistors were of suitable magnitude and opposite in phase. This requirement can be achieved if the driver transistor is connected as shown in Fig. 2.

This method of connection also meets one of the most important requirements of a low distortion amplifier - that the basic linearity of the amplifier should be good, even in the absence of feedback. Several factors contribute to this. There is the tendency of the lC/Vb non-linearity of the characteristics of the output transistors to cancel, because during the part of the cycle in which one transistor is approaching cut-off the other is turned full on. There is a measure of internal feedback around the loop Tr1, Tr2, Tr3 because of the effect which the base impedance characteristics of Tr1 have on the output current of Tr3. Also, the driver transistor Tr3, which has to deliver a large voltage swing, is operated under conditions which favour low harmonic distortion - low output load impedance, high input impedance. A practical power amplifier circuit using this type of output stage is shown in Fig. 3.

The open loop gain of the circuit is approximately 600 with typical transistors. The closed loop gain is determined, at frequencies high enough for the impedance of C3 to be small in comparison to R4, by the ratio (R3 + R4)/R4. With the values indicated in Fig. 3, this is 13. This gives a feedback factor of some 34dB, and an output impedance of about 160 milliohms.

Since the circuit has unity gain at d.c., because of the inclusion of C3 in the feedback loop, the output voltage, Ve, is held at the same potential as the base of Tr4 plus the base emitter potential of Tr4 and the small potential drop along R3 due to the emitter current of this transistor. Since the output transistor Tr1 will turn on as much current as is necessary to pull Ve down to this value, the resistor R2, which together with R1 controls the collector current of Tr2, can be used to set the static current of the amplifier output stages. It will also be apparent that Ve can be set to any desired value by small adjustments to R5 or R6. The optimum performance will be obtained when this is equal to half the supply voltage. (Half a volt or so either way will make only a small difference to the maximum output power obtainable, and to the other characteristics of the amplifier, so there is no need for great precision in setting this.)

Silicon planar transistors are used throughout, and this gives good thermal stability and a low noise level. Also, since there is no requirement for complementary symmetry, all the power stages can use n-p-n transistors which offer, in silicon, the best performance and lowest cost. The overall performance at an output level of 10 watts, or at any lower level, more than meets the standards laid down by Williamson. The power output and gain/frequency graphs are shown in Figs. 4 - 6, and the relationship between output power and total harmonic distortion is shown in Fig. 7. Since the amplifier is a straight-forward class A circuit, the distortion decreases linearly with output voltage. (This would not necessarily be the case in a class B system if any significant amount of cross-over distortion was present.) The analysis of distortion components at levels of the order of 0.05% is difficult, but it appears that the residual distortion below the level at which clipping begins is predominantly second harmonic.

**Stability, power output and load impedance**

Silicon planar n-p-n transistors have, in general, excellent high frequency characteristics, and these contribute to the very good stability of the amplifier with reactive loads. The author has not yet found a combination of L and C which makes the system unstable, although the system will readily become oscillatory with an inductive load if R3 is shunted by a small condenser to cause roll-off at high frequencies.
The circuit shown in Fig. 3 may be used, with very little modification to the component values, to drive load impedances in the range 3 - 15 ohms. However, the chosen output power is represented by a different current/voltage relationship in each case, and the current through the output transistors and the output-voltage swing will therefore also be different. The peak-voltage swing and mean output current can be calculated quite simply from the well-known relationships \( W = I^2 \cdot R \) and \( V = I \cdot R \), where the symbols have their customary significance. (It should be remembered, however, that the calculation of output power is based on r.m.s. values of current and voltage, and that these must be multiplied by 1.414 to obtain the peak values, and that the voltage swing measured is the peak-to-peak voltage, which is twice the peak value.)

When these calculations have been made, the peak-to-peak voltage swing for 10 watts power into a 15-Ohm load is found to be 34.8 volts. Since the two output transistors bottom at about 0.6 volts each, the power supply must provide a minimum of 36 volts in order to allow this output. For loads of 8 and 3 ohms, the minimum h.t. line voltage must be 27V and 17 volts respectively. The necessary minimum currents are 0.9, 1.2 and 2.0 amps. Suggested component values for operation with these load impedances are shown in Table 1. C3 and C1 together influence the voltage and power roll-off at low audio frequencies. These can be increased in value if a better low-frequency performance is desired than that shown in Figs. 4 - 6.

Since the supply voltages and output currents involved lead to dissipations in the order of 17 watts in each output transistor, and since it is undesirable (for component longevity) to permit high operating temperatures, adequate heat sink area must be provided for each transistor. A pair of separately mounted 5in by 4in finned heatsinks is suggested. This is, unfortunately, the penalty which must be paid for class A operation. For supplies above 30V Tr1 and Tr2 should be MJ481s and Tr3 a 2N1613.

If the output impedance of the pre-amplifier is more than a few thousand ohms, the input stage of the amplifier should be modified to include a simple f.e.t. source follower circuit, as shown in Fig. 8. This increases the harmonic distortion to about 0.12%, and is therefore (theoretically) a less attractive solution than a better pre-amplifier. A high frequency roll-off can then be obtained, if necessary, by connecting a small capacitor between the gate of the f.e.t. and the negative (earthly) line.

<table>
<thead>
<tr>
<th>( Z_L )</th>
<th>( V )</th>
<th>( I )</th>
<th>R1</th>
<th>R2</th>
<th>C1</th>
<th>C2</th>
<th>( V_{IN} ) (rms)</th>
</tr>
</thead>
<tbody>
<tr>
<td>3( \Omega )</td>
<td>17V</td>
<td>2.0A</td>
<td>47( \Omega )</td>
<td>180( \Omega )</td>
<td>500( \mu F )</td>
<td>25V</td>
<td>5000( \mu F )</td>
</tr>
<tr>
<td>8( \Omega )</td>
<td>27V</td>
<td>1.2A</td>
<td>100( \Omega )</td>
<td>560( \Omega )</td>
<td>250( \mu F )</td>
<td>40V</td>
<td>2500( \mu F )</td>
</tr>
<tr>
<td>15( \Omega )</td>
<td>36V</td>
<td>0.9A</td>
<td>150( \Omega )</td>
<td>1.2k( \Omega )</td>
<td>250( \mu F )</td>
<td>40V</td>
<td>2500( \mu F )</td>
</tr>
</tbody>
</table>

**Table 1. Summary of component combinations for different load impedances.**

**Suitable transistors**

Some experiments were made to determine the extent to which the circuit performance was influenced by the type and current gain of the transistors used. As expected the best performance was obtained when high-gain transistors were used, and when the output stage used a matched pair. No adequate substitute is known for the 2N697 / 2N1613 type used in the driver stage, but examples of this transistor type from three different manufacturers were used with apparently identical results. Similarly, the use of alternative types of input transistor produced no apparent performance change, and the Texas Instruments 2N4058 is fully interchangeable with the Motorola 2N3906 used in the prototype.

The most noteworthy performance changes were found in the current gain characteristics of the output transistor pair, and for the lowest possible distortion with any pair, the voltage at the point from which the loudspeaker is fed should be adjusted so that it is within 0.25 volt of half the supply line potential. The other results are summarized in Table 2.

The transistors used in these experiments were Motorola MJ480 / 481, with the exception of (6), in which Texas 2S034 devices were tried. The main conclusion which can be drawn from this is that the type of transistor used may not be very important, but that if there are differences in the current gains of the output transistors, it is necessary that the device with the higher gain shall be used in the position of Tr1.
When distortion components were found prior to the onset of waveform clipping, these were almost wholly due to the presence of second harmonics.

<table>
<thead>
<tr>
<th>Test No.</th>
<th>Current Gain Tr1</th>
<th>Current Gain Tr2</th>
<th>Distortion (at 9 watts)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>135</td>
<td>135</td>
<td>0.06%</td>
</tr>
<tr>
<td>2</td>
<td>40</td>
<td>120</td>
<td>0.4%</td>
</tr>
<tr>
<td>3</td>
<td>120</td>
<td>40</td>
<td>0.12% (pair 2 reversed)</td>
</tr>
<tr>
<td>4</td>
<td>120</td>
<td>100</td>
<td>0.09%</td>
</tr>
<tr>
<td>5</td>
<td>100</td>
<td>120</td>
<td>0.18% (pair 5 reversed)</td>
</tr>
<tr>
<td>6</td>
<td>50</td>
<td>40</td>
<td>0.1%</td>
</tr>
</tbody>
</table>

Table 2. Relation of distortion to gain-matching in the output stage.

Construcional notes

**Amplifier.** The components necessary for a 10 + 10 watt stereo amplifier pair can be conveniently assembled on a standard “Lektrokit” 4in x 4.75in s.r.b.p. pin board, as shown in the photographs, with the four power transistors mounted on external heat sinks. Except where noted the values of components do not appear to be particularly critical, and 10% tolerance resistors can certainly be used without ill effect. The lowest noise levels will however be obtained with good quality components, and with carbon-film, or metal-oxide, resistors.

**Power Supply.** A suggested form of power supply unit is shown in Fig. 9(a). Since the current demand of the amplifier is substantially constant, a series transistor smoothing circuit can be used in which the power supply output voltage may be adjusted by choice of the base current input provided by the emitter follower Tr2 and the potentiometer VR1. With the values of the reservoir capacitor shown in Table 3, the ripple level will be less than 10mV at the rated output current, provided that the current gain of the series transistors is greater than 40. For output currents up to 2.5 amps, the series transistors indicated will be adequate, provided that they are mounted on heat sinks appropriate to their loading.

However, at the current levels necessary for operation of the 3-ohm version of the amplifier as a stereo pair, a single MJ480 will no longer be adequate, and either a more suitable series transistor must be used, such as the Mullard BDY20, with for example a 2N1711 as Tr2, or with a parallel connected arrangement as shown in Fig. 9(b).

<table>
<thead>
<tr>
<th>Amp ZL</th>
<th>IOUT</th>
<th>VOUT</th>
<th>C1</th>
<th>Tr1/2</th>
<th>MR1</th>
<th>T1</th>
</tr>
</thead>
<tbody>
<tr>
<td>15Ω</td>
<td>1A</td>
<td>37V</td>
<td>1000µF</td>
<td>MJ480 / 2N697</td>
<td>5BO5</td>
<td>40V</td>
</tr>
<tr>
<td>2 x 15Ω</td>
<td>2A</td>
<td>37V</td>
<td>5000µF</td>
<td>MJ480 / 2N697</td>
<td>5BO5</td>
<td>40V</td>
</tr>
<tr>
<td>8Ω</td>
<td>1.25A</td>
<td>27V</td>
<td>2000µF</td>
<td>MJ480 / 2N697</td>
<td>5BO5</td>
<td>30V</td>
</tr>
<tr>
<td>2 x 8Ω</td>
<td>2.5A</td>
<td>27V</td>
<td>5000µF</td>
<td>MJ480 / 2N697</td>
<td>5BO5</td>
<td>30V</td>
</tr>
<tr>
<td>3Ω</td>
<td>1.9A</td>
<td>18V</td>
<td>5000µF</td>
<td>MJ480 / 2N697</td>
<td>5BO5</td>
<td>20V</td>
</tr>
<tr>
<td>2 x 3Ω</td>
<td>3.8A</td>
<td>18V</td>
<td>10,000µF</td>
<td>MJ480 / 2x2N697</td>
<td>7BO5T</td>
<td>20V</td>
</tr>
</tbody>
</table>

Table 3. Power-supply components

The total resistance in the rectifier “primary” circuit, including the transformer secondary winding, must not be less than 0.25Ω. When the power supply, with or without an amplifier, is to be used with an r.f. amplifier-tuner unit, it may be necessary to add a 0.25uF (160V.w.) capacitor across the secondary winding of T1 to prevent transient radiation. The rectifier diodes specified are International Rectifier potted bridge types.
Transistor protection circuit

The current which flows in the output transistor chain (Tr1, Tr2) is determined by the potential across Tr2, the values of R1 and R2, and the current gain and collector-base leakage current of Tr2. Since both these transistor characteristics are temperature dependant the output series current will increase somewhat with the temperature of Tr2. If the amplifier is to be operated under conditions of high ambient temperature, or if for some reason it is not practicable to provide an adequate area of heat-sink for the output transistors, it will be desirable to provide some alternative means for the control of the output transistor circuit current. This can be done by means of the circuit shown in Fig. 10. In this, some proportion of the d.c. bias current to Tr1 is shunted to the negative line through Tr7, when the total current flowing causes the potential applied to the base of Tr6 to exceed the turn-on value (about 0.5 volt). This allows very precise control of the series current without affecting the output power or distortion characteristics. The simpler arrangement whereby the current control potential for Tr7 is obtained from a series resistor in the emitter circuit of Tr1 leads, unfortunately, to a worsening of the distortion characteristics to about 0.15% at 8 watts, rising to about 0.3% at the onset of overload.

Performance under listening conditions

It would be convenient if the performance of an audio amplifier (or loudspeaker or any other similar piece of audio equipment) could be completely specified by frequency response and harmonic distortion characteristics. Unfortunately, it is not possible to simulate under laboratory conditions the complex loads or intricate waveform structures presented to the amplifier when a loudspeaker system is employed to reproduce the everyday sounds of speech and music; so that although the square wave and low-distortion sine wave oscillators, the oscilloscope, and the harmonic distortion analyser are valuable tools in the design of audio circuits, the ultimate test of the final design must be the critical judgement of the listener under the most carefully chosen conditions his facilities and environment allow.

The possession of a good standard of reference is a great help in comparative trials of this nature, and the author has been fortunate in the possession, for many years, of a carefully and expensively built “Williamson” amplifier, the performance of which has proved, in listening trials, to equal or exceed, by greater or lesser margins, that of any other audio amplifier with which the author has been able to make comparisons.

However, in the past, when these tests were made for personal curiosity, and some few minutes could elapse in the transfer of input and output leads from one amplifier to the other, the comparative performance of some designs has been so close that the conclusion drawn was that there was really very little to choose between them. Some of the recent transistor power amplifier circuits gave a performance which seemed fully equal to that of the “Williamson”, at least so far as one could remember during the interval between one trial and the next. It was, however, appreciated that this did not really offer the best conditions for a proper appraisal of the more subtle differences in the performance of already good designs, so a changeover switch was arranged to transfer inputs and outputs between any chosen pair of amplifiers, and a total of six amplifier units was assembled, including the “Williamson”, and another popular valve unit, three class B transistor designs, including one of commercial origin, and the class A circuit described above. The frequency response, and total harmonic distortion characteristics, of the four transistor amplifiers was tested in the laboratory prior to this trial, and all were found to have a flat frequency response through the usable audio spectrum, coupled with low harmonic distortion content (the worst-case figure was 0.15%).

In view of these prior tests, it was not expected that there would be any significant difference in the audible performance of any of the transistor designs, or between them and the valve amplifiers. It was therefore surprising to discover, in the event, that there were discernable differences between the valve and the three class B transistor units. In fact, the two valve designs and the class A transistor circuit, and the three class B designs formed two tonally distinct groups, with closely similar characteristics within each group.
The “Williamson” and the present class A design were both better than the other valve amplifier, and so close in performance that it was almost impossible to tell which of the two was in use without looking at the switch position. In the upper reaches of the treble spectrum the transistor amplifier has perhaps a slight advantage.

The performance differences between the class A and the class B groups were, however, much more prominent. Not only did the class A systems have a complete freedom from the slight “edginess” found on some high string notes with all the class B units, but they appeared also to give a fuller, “rounder”, quality, the attractiveness of which to the author much outweighs the incidental inconvenience of the need for more substantial power supply equipment and more massive heat sinks.

Some thought, in discussions with interested friends, has been given to the implications of this unlooked-for discovery, and a tentative theory has been evolved which is offered for what it is worth. It is postulated that these tonal differences arise because the normal moving-coil loudspeaker, in its associated housing, can present a very complex reactive load at frequencies associated with structural resonances, and that this might provoke transient overshoot when used with a class B amplifier, when a point of inflection in the applied waveform chanced to coincide with the point of transistor crossover, at which point, because of the abrupt change in the input parameters of the output transistors the loop stability margins and output damping will be less good. In these circumstances, the desired function of the power-amplifier output circuit in damping out the cone-response irregularities of the speaker may be performed worse at the very places in the loudspeaker frequency-response curve where the damping is most needed.

It should be emphasized that the differences observed in these experiments are small, and unlikely to be noticed except in direct side-by-side comparison. The perfectionist may, however, prefer class A to class B in transistor circuitry if he can get adequate power for his needs that way.

Listener fatigue

In the experience of the author, the performance of most well-designed audio power amplifiers is really very good, and the differences between one design and another are likely to be small in comparison with the differences between alternative loudspeaker systems, for example, and of the transistor designs so far encountered, not one could be considered as unpleasing to the ear. However, with the growing use of solid-state power amplifiers, puzzling tales of “listener fatigue” have been heard among the cognoscenti, as something which all but the most expensive transistor amplifiers will cause the listener, in contradistinction with good valve-operated amplifiers. This seemed to be worth investigation, to discover whether there was any foundation for this allegation.

In practice it was found that an amplifier with an impeccable performance on paper could be quite worrying to listen to under certain conditions. This appears to arise and be particularly associated with transistor power amplifiers because most of these are easily able to deliver large amounts of power at supersonic frequencies, which the speakers in a high quality system will endeavour to present to the listener. In this context it should be remembered that in an amplifier which has a flat power response from 30Hz to 180kHz, 90% of this power spectrum will be supersonic.

This unwanted output can arise in two ways. It can be because of wide spectrum “white noise” from a preamplifier with a significant amount of hiss – this can happen if a valve preamplifier is mismatched into the few thousand ohms input impedance of a transistor power amplifier, and will also cause the system performance to be unnaturally lacking in bass. Trouble of this type can also arise if transient instability or high frequency “ringing” occurs, for example when a reactive load is used with a class B amplifier having poor cross-over point stability.

Reference

Figures

Fig. 1. Basic class A circuits using (a) load resistor $R_c$ giving power conversion efficiency of about 12%, (b) l.f. choke giving better efficiency but being bulky and expensive, and (c) a second transistor as collector load.

Fig. 2. Arrangement for push-pull drive of class A stage.

Fig. 3. Practical power amplifier circuit.
Fig. 4. Gain/frequency response curve of amplifier.

Fig. 5. Output power/frequency response curve of amplifier.

Fig. 6. Distortion/frequency curve at 9W.

Fig. 7. Distortion/output power curve.
Fig. 8. Modified input circuit for high input impedance.

Fig. 9. (a) Power supply unit, and (b) parallel connected transistors for high currents.

Fig. 10. Amplifier current regulation circuit.
Simple Class A Amplifier

A 10-W design giving subjectively better results than class B transistor amplifiers

by J. L. Linsley Hood, M.I.E.E.

Oscilloscope Traces

Sine wave performance at 1kHz. 9 watts; 15 ohm resistive load. Fundamental on scale of 10V/cm. Distortion components on scale of 50mV/cm with r.m.s. value of 0.05%.

Square wave response at 50Hz.

Square wave response. Scale 10V/cm. Frequency 50kHz. 15 ohm resistive load.
Photographs

Layout of single channel of 10 + 10 watt amplifier on standard 4in × 4½in 'Lakrokit' s.r.b.p. pin board.

Underside of completed amplifier, with base cover removed, showing external box-form heat sink.

Looking down on the completed amplifier.
Letters to the Editor

Linsley Hood class A amplifier

Recent measurements on this amplifier have indicated that the gain and power bandwidths of this design, using the component layout shown on page 152 of your April 1969 issue, are wider than indicated by the Figs. 4 and 5 of the article. The apparent fall-off in gain beyond about 100kHz was, in fact, due to shortcomings in the measuring apparatus, and measurements made with better equipment suggest that the −3dB points for voltage gain are above 1.5MHz although the power output falls beyond 200kHz.

Since the output is in phase with the input, it is necessary to take care that the output leads and the output capacitor are not close to the input. (A 2-inch separation will be adequate for normal lead lengths.) However, an additional point must also be noted. If a capacitive load is connected with short leads between the output and the earth line near the input connection, the potential developed along the earth line, due to its inductance, can inject an in-phase signal, and thereby cause instability, in the MHz region. To avoid this possibility, it is recommended that the earthy lead to the loudspeaker terminal be returned to the earth line at the same point as the emitter of Tr1. The inclusion of a small r.f. choke (25 turns of 26-28 s.w.g. wire wound round the outside of a 10-ohm 1-watt resistor is ideal) between the output (point ‘X’) and C2 will also prevent this possibility of trouble.

In practice, with the components and layout suggested, the inductance of the normal 12 to 18 inches (or more) of loudspeaker connecting lead prevents instability with capacitive loads, so this should be only of academic interest.

As an alternative, it is possible to reduce the r.f. response of the amplifier to give a smooth 6dB roll-off beyond 50kHz – which removes much of the need for care in the layout of components, without detriment to the harmonic distortion in the audible range, and without any audible alteration to the performance – by connecting a 1,000pF capacitor between the collector of Tr3 and the emitter of Tr4; a 1,000pF in series with 100 ohms between the collector of Tr4 and earth; and a 0.01µF in series with 8 to 10 ohms between the output (‘X’) and earth. (It should be noted that either all of these components should be added or none at all, they are not alternatives.) If the r.f. response is reduced in this manner, the use of a series r.f. choke would be unnecessary.

A series of measurements has also been made, using the amplifier design exactly as described in the article (without r.f. chokes or other modifications), to determine the voltage waveform produced, actually across the loudspeaker, with a square wave input to the amplifier. It was found, in practice, with several different loudspeaker systems, that the output waveform was virtually identical to that obtained with an equivalent resistive load – photographs of which were reproduced in the April issue. It was, in fact, the discovery that a good square wave was reproduced up to the 1MHz limit of the generator in use which prompted a reassessment of the r.f. response of the amplifier. The absence of any overshoot or significant ringing also provides confirmation of the stability of the amplifier under practical conditions.

A correspondent has reported that this design has been up-rated successfully to 15 watts into a 15-ohm load, to give a direct power equivalent to the Williamson amplifier, using 2N3055 output transistors with a 43-volt supply (1.1 amp per channel), and rather larger heatsinks. There would seem no good reason why this could not also be done using MJ481s.

J. L. LINSLEY HOOD
Mr Linsley Hood’s amended circuit of his class A amplifier originally described in the April 1969 issue.
Simple Class A Amplifier

A postscript to the design published last year

by J. L. Linsley Hood

The author has had the benefit of an extensive and frequently helpful correspondence with readers following the publication of the circuit design. Attention has been drawn to some obscurities in the original article and to certain possible improvements in the design. Details are given below.

Power supply

Although much interest was aroused among constructors by the good technical (and audible) performance given by the amplifier, it is clear that the principal feature in the eyes of many users was the relative simplicity of the circuit. This being so it must have seemed a pity that the power-supply unit was somewhat complex. However, the purpose of this power-supply design was to avoid possible degradation of the amplifier performance by h.t. ripple. The sawtooth ripple voltage across the reservoir capacitor in a class-A amplifier drawing some 2-3A will be many times greater than in a class-B system, particularly at the audibly important low-signal levels.

However, a number of measurements have been made since the publication of the original article on an amplifier of this type, operated from a simple supply unit of the type shown in Fig. 1. There is little difference in the performance above 100Hz either in total harmonic distortion or in intermodulation distortion, although the shape of the output power/distortion curve at the onset of overload is modified, as would be expected, by the ripple on the h.t. line. Below 100Hz the distortion curve rises more steeply to about 0.2% at 20Hz.

A thermistor is necessary, in this case, to slow down the rate of rise of the h.t. voltage. This will get hot in use.

It now appears that the mains transformers used in the development of the prototype of this amplifier were not as efficient in respect of apparent secondary circuit resistance or secondary leakage reactance as some of those which have been supplied for this purpose since the publication of the article. The reservoir voltage found with the 15Ω system may be above that given by the author. At switch-on this can cause a transient overloading of the transistors specified for the series regulator circuit in the original article. In view of this, it is suggested that these should be an MJ481 or 2N3055, used in conjunction with a 2N1613 or, better still, a 2N699. These amendments are shown in Fig. 2.

Adjustment of amplifier output current and centre-line potential

The author had supposed, somewhat naively, that most constructors of the circuit would have somewhere in their workshops a collection of odd-value resistors needed for trimming circuit parameters, and it was mentioned in the original article that the desired quiescent levels could be set by adjustment to R2 and R5 or R6. This sort of comment is unhelpful if one is writing away for a kit of parts. In view of this it is suggested that R2 should be replaced by a resistor in series with a potentiometer, as shown in Fig. 1. The necessary value of resistors R5 and R6 to give an entirely adequate accuracy in the mid-point voltage setting can be predicted, and the suggested amended values are shown.

Some obscurity arose, inadvertently, in the original diagram concerning the reason for the different values of input decoupling resistor quoted for mono and stereo use. This was because it was intended that the one decoupling circuit should serve both channels. Where an unsmoothed h.t. supply is used it is recommended that the decoupling capacitor should be increased in value to 250μF.
Stability of output current setting

Some criticism has been voiced because there is no specific control over the output current value in the simplest form of this circuit, other than that due to the stability of the current gain of Tr2, whose performance determines this parameter. In order to meet this point (in anticipation) a circuit was described in the original article which allowed precise control over the operating ‘quiescent’ current without detriment to the performance of the amplifier.

However, measurements made on an amplifier without this addition have shown no significant change in operating current in somewhat over two years use, and there is also little measurable difference in current from a minute or so after switch-on to the end of a six-hour period of continuous use. In practice therefore, in temperate climates at least, the simplest form of the circuit is adequate in this respect. If any user cares to experiment with an alternative and somewhat more elegant form of quiescent-current control another regulation circuit is shown in Fig. 3. The transistor used as Tr5 requires to be somewhat more massive than that used for Tr3 since the mean collector current is twice that of Tr3 and the maximum voltage and current occur simultaneously. The 2N2905A is just about adequate with a good heatsink, but a larger power device such as the 2N4919 is preferable.

Alternative transistor types

The amplifier has been built successfully with a wide variety of transistors, including fully complementary versions to operate from an existing negative h.t. line, and in one case two identical amplifiers have been made for use with the inputs in paraphase, in order to double the available output voltage swing. One constructor has, indeed, made a stereo 30W system using two such pairs of amplifiers plus input phase splitter, as shown in Fig. 4.

However, one transistor change which is recommended is the use of a 2N1711 as Tr3. This has a high voltage capability equal to that of the 2N1613, and a current gain which is double that of either the 2N1613 or the 2N697. The use of the 2N1711 instead of the former types suggested for Tr3 increases the feedback factor and approximately halves the typical distortion factor of the system (0.025% at 9W or 0.05% at full power) without detriment in other respects.

Also, a 2N1711 as Tr3 allows the use of 2N3055 devices as Tr1 and Tr2, with a final performance which is equal to that of the original specification below 100kHz. (The typical current gain of the 2N3055s is only half that normally found with the MJ480/1 output transistors, and their use was not originally recommended for this reason.)

Gain/frequency and power/frequency characteristics

These are, in fact, better than the curves published in April 1969. As mentioned in a letter to the editor published in October 1969, the h.f. fall-off shown was mainly due to an error in the measurement instrument. Although the performance at h.f. depends to some extent on the layout employed, the small signal voltage gain, with the component arrangement shown, is flat (within 1dB) to beyond 2MHz. This may be a snag in some cases because even a small feedback capacitance between output and input (as may happen, for example, if the output heatsinks are not earthed) may cause the amplifier to oscillate. A suitable circuit change to reduce the amplifier h.f. response to more normal levels was described in the letter above. This is not an essential modification – the author’s own units are still exactly as described in April 1969.

The output power response of the unmodified amplifier is flat within 1dB to 200kHz.

The l.f. response shown in the original gain/frequency and power/frequency graphs was that determined for an earlier prototype of the amplifier. During the development of the circuit the values of some of the capacitors were increased to improve the l.f. performance, and by an oversight the graphs accompanying the article were not amended. In fact the gain and power graphs can be shown as ‘flat’ from 10Hz-200kHz. In this respect, and that of transient response, the class-A design is probably better than any circuit so far published. The i.m. distortion, at 10W output, (70Hz and 7kHz, 4:1) is less than 0.1%.
Miscellaneous

Surprise – and even alarm – has been caused to some constructors by the fact that the output transistors get hot. However, with adequate heatsinks, which should be black painted, the dissipations in the transistors are only a small fraction of the maker’s permitted level, and provided that some care is taken in the layout to make sure that sensitive components, such as electrolytic capacitors, remain cool, no reduction in the working life of such a system, in comparison with an equivalent class-B unit for example, is to be expected.

Some difficulty has apparently been encountered by some constructors because the power supply regulation system is inoperative when the supply is operated without a load. If an equivalent resistive dummy load is connected for bench-testing, all should be found to be well.

Finally, it is prudent to wire a small resistor of about 2kΩ across the loudspeaker terminals to make sure that the output capacitor charges even with the speaker disconnected. Charging of the capacitor by an accidental short-circuit could cause damage. This addition is shown in Fig. 1. No damage is caused by operating the amplifier on an o / c output.

Figures

**Fig. 1. Suggested amended circuit for 8 or 15Ω use employing a simplified power supply. The dotted components reduce the h.f. response and should be used with capacitive loads.**
Fig. 2. Amended circuit of power supply for 15Ω systems.

Fig. 3. Alternative method of quiescent-current control. R1, R2 and C1 in the original have been deleted. Tr5 is 2N4919 on heatsink or alternative type.

Fig. 4. Scheme for 30W class-A system. The two identical class-A amplifiers, each designed to give 15W into 8Ω (34V at 1.5A), are driven by a phase-splitter. The output capacitors have been removed.